



FEASIBILITY OF DISTANCE-REGULAR GRAPHS



By
MISS Supalak SUMALROJ

A Thesis Submitted in partial Fulfillment of Requirements
for Doctor of Philosophy (MATHEMATICS)
Department of MATHEMATICS
Graduate School, Silpakorn University
Academic Year 2017
Copyright of Graduate School, Silpakorn University

FEASIBILITY OF DISTANCE-REGULAR GRAPHS



A Thesis Submitted in Partial Fulfillment of the Requirements
for Doctor of Philosophy (MATHEMATICS)

Department of MATHEMATICS

Graduate School, Silpakorn University

Academic Year 2017

Copyright of Graduate School, Silpakorn University

Title Feasibility of distance-regular graphs
By Supalak SUMALROJ
Field of Study (MATHEMATICS)
Advisor Chalermpong Worawannotai

Science Silpakorn University in Partial Fulfillment of the Requirements
for the Doctor of Philosophy

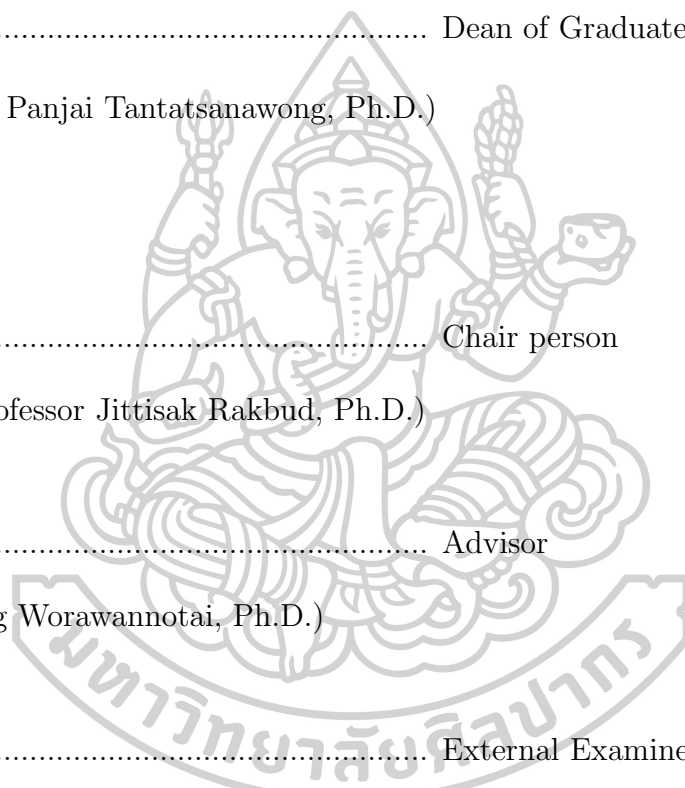
..... Dean of Graduate School
(Assoc. Prof. Panjai Tantatsanawong, Ph.D.)

Approved by

..... Chair person
(Assistant Professor Jittisak Rakbud, Ph.D.)

..... Advisor
(Chalermpong Worawannotai, Ph.D.)

..... External Examiner
(Assistant Professor Wongsakorn Charoenpanitseri, Ph.D.)



56305803 : MAJOR (MATHEMATICS)

KEY WORDS : DISTANCE-REGULAR GRAPH, LOCAL GRAPH, NONEXISTENCE, PARTIAL LINEAR SPACE

SUPALAK SUMALROJ : FEASIBILITY OF DISTANCE-REGULAR GRAPHS. THESIS ADVISOR : CHALERMPONG WORAWANNOTAI, Ph.D.

The problem of deciding whether a distance-regular graph with a given intersection array exists is a widely studied topic in distance-regular graphs. In 1989 Brouwer, Cohen and Neumaier have compiled a list of intersection arrays that passed known feasibility conditions, but the existence of corresponding distance-regular graphs were unknown for many of those arrays. Since then the arrays from the list are studied and the existence and nonexistence of distance-regular graphs associated to many arrays from the list are proved but more than half are still unknown.

In this thesis, we study three intersection arrays from the list, $\{22, 16, 5; 1, 2, 20\}$, $\{27, 20, 10; 1, 2, 18\}$, and $\{36, 28, 4; 1, 2, 24\}$. We prove that distance-regular graphs with these intersection arrays do not exist. To prove these, we assume that such graphs exist and derive some combinatorial properties of their local graphs to get contradictions.

Acknowledgements

This thesis has been completed by the involvement of people about whom I would like to mention here.

I would like to express my deep gratitude to my thesis advisor, Dr. Chalermpong Worawannotai, for insightful suggestions on my work. He encouraged and advised me through the thesis process.

I also would like to thank to my thesis committees, Assistant Professor Dr. Jittisak Rakbud and Assistant Professor Dr. Wongsakorn Charoenpanitseri for their comments and suggestions.

Moreover, I would like to thank all the teachers who have instructed and taught me for valuable knowledge.

In addition, I would like to thank the Development and Promotion of Science and Technology Talents Project (DPST) for financial support throughout my undergraduate and graduate study.

Finally, I would like to thank my family, my friends and those whose names are not mentioned here but have greatly inspired and encouraged me throughout the period of this research.

Supalak SUMALROJ

Table of contents

	page
Abstract	iii
Acknowledgements	iv
Table of contents	v
List of Tables	vi
List of Figures	vii
Chapter	
1 Introduction	1
2 Distance-regular graphs	7
3 The nonexistence of a distance-regular graph with intersection array {27, 20, 10; 1, 2, 18}	11
4 The nonexistence of a distance-regular graph with intersection array {36, 28, 4; 1, 2, 24}	14
5 The nonexistence of a distance-regular graph with intersection array {22, 16, 5; 1, 2, 20}	19
6 Conclusions	30
References	31
Publications	33
Biography	34

List of tables

Tables	page
5.3 The 8 possibilities for the degree sequence of R	23



List of figures

Figures	page
1.1 Distribution diagram for a distance-regular graph with intersection array $\{b_0, \dots, b_{d-1}; c_1, \dots, c_d\}$	3
1.2 The Heawood graph	3
1.3 Distribution diagram for the Heawood graph	3
1.4 Illustration for the sets $\Gamma_i(x)$ of the Heawood graph	3
1.5 The Fano plane	5
3.1 Distribution diagram for a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$	11
3.2 The 3 possibilities for the subgraph of Δ induced by a vertex w and its neighbors	13
4.1 Distribution diagram for a distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$	14
4.2 The 6 possibilities for the subgraph of Δ induced by a vertex u and its neighbors	15
5.1 Distribution diagram for a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$	19
5.2 The 3 possibilities for the subgraph of Δ induced by a vertex u and its neighbors	20
5.4 The 3 possibilities for the incidence geometry G	27

Chapter 1

Introduction

The problem of deciding whether a distance-regular graph with a given intersection array exists is a widely studied topic in distance-regular graphs. In 1989 Brouwer, Cohen and Neumaier [5] have compiled a list of intersection arrays that passed known feasibility conditions, but the existence of corresponding distance-regular graphs were unknown for many of those arrays. Since then the arrays from the list are studied and the existence and nonexistence of distance-regular graphs associated to many arrays from the list are proved [11, Section 17] but more than half are still unknown.

In this chapter we intend to recall some definitions and notations used in this thesis. Most of them follows Biggs [2], Bondy and Murty [3], and Brouwer, Cohen and Neumaier [5].

A *graph* is an ordered pair $\Gamma = (V(\Gamma), E(\Gamma))$ where $V(\Gamma)$ is a nonempty set of elements called *vertices* and $E(\Gamma)$ is a set of unordered pairs of (not necessary distinct) vertices called *edges*. For any edge $e = \{x, y\} \in E(\Gamma)$, we say that x and y are *adjacent* and we write $e = xy$. The vertices x and y are called the *end vertices* of an edge e . We say that the vertices x and y are *incident* with an edge e . A graph Γ is said to be *finite* whenever both $V(\Gamma)$ and $E(\Gamma)$ are finite. The *order* of a graph Γ is the number of vertices of Γ . An edge is called a *loop* whenever it has identical end vertices. Two or more edges that join the same end vertices are called *parallel edges*. A *simple graph* is a graph having no loops or parallel edges. All graphs we consider are finite and simple.

A graph Γ' is a *subgraph* of a graph Γ whenever $V(\Gamma') \subseteq V(\Gamma)$ and $E(\Gamma') \subseteq E(\Gamma)$. For a nonempty subset S of $V(\Gamma)$, the *subgraph of Γ induced by S* , is a graph with vertex set S and edge set $\{xy \in E(\Gamma) | x, y \in S\}$. For a subset S

of $V(\Gamma)$, the *neighborhood* of S in Γ , denoted by $N_\Gamma(S)$, is the set of all vertices in $\Gamma - S$ that are adjacent to at least one vertex of S . A *neighborhood* of a vertex x in Γ , denoted by $N_\Gamma(x)$, is the set $\{y \in V(\Gamma) | xy \in E(\Gamma)\}$. The *degree* of x in Γ is $|N_\Gamma(x)|$. For any graph Γ , we identify Γ with its vertex set $V(\Gamma)$. We denote the subgraph of Γ induced by a subset S of $V(\Gamma)$ by S itself. For a vertex x in Γ , the subgraph of Γ induced by the neighbors of x is called the *local graph* of Γ with respect to x .

A *walk* in a graph is a finite sequence $x_0e_1x_1e_2 \dots e_{n-1}x_{n-1}e_nx_n$ of vertices and edges such that for $1 \leq i \leq n$, the edge e_i has end vertices x_{i-1} and x_i . A *path* is a walk with distinct vertices. A walk $C = x_0e_1x_1e_2 \dots e_{n-1}x_{n-1}e_nx_0$ is called a *cycle* whenever the edges e_1, e_2, \dots, e_n and the vertices x_0, x_1, \dots, x_{n-1} of C are distinct and C has at least 3 edges. A cycle C has *length* n , denoted by C_n , if the number of edges of C is n . We may write a cycle $x_0e_1x_1e_2 \dots e_{n-1}x_{n-1}e_nx_0$ by $x_0x_1 \dots x_{n-1}$. Two vertices x and y are *connected* whenever there exists a path from x to y . We say that a graph Γ is *connected* whenever every pair of its vertices are connected; otherwise Γ is *disconnected*. For vertices x and y in Γ , the *distance* between x and y , denoted by $d(x, y)$ is the length of a shortest path between x and y in Γ . The *diameter* of Γ , denoted by $diam(\Gamma)$, is the greatest distance between any pair of vertices in Γ . A *complete graph* is a simple graph in which any two distinct vertices are adjacent. A complete graph with n vertices is denoted by K_n . A *clique* of a graph Γ is a maximal complete subgraph of Γ . A *coclique* of a graph Γ is a nonempty induced subgraph of Γ with an empty set of edges.

A *regular graph* is a graph such that each vertex has the same degree. For an integer $k \geq 0$, a graph is *k-regular* whenever every vertex has degree k ; in other words, a graph has *valency* k . Let Γ denote a connected graph with diameter d . For a vertex $x \in V(\Gamma)$ and $0 \leq i \leq d$ let $\Gamma_i(x)$ denote the set of vertices at distance i from x . The graph Γ is called *distance-regular* whenever for all $0 \leq i \leq d$ and any two vertices x and y and distance $d(x, y) = i$, the numbers $b_i = |\Gamma_{i+1}(x) \cap \Gamma_1(y)|$, $c_i = |\Gamma_{i-1}(x) \cap \Gamma_1(y)|$ and $a_i = |\Gamma_i(x) \cap \Gamma_1(y)|$ depend only on i where $\Gamma_{-1}(x)$ and $\Gamma_{d+1}(x)$ are unspecified. The numbers b_i, c_i and a_i are called

the *intersection numbers* of Γ . For $0 \leq i \leq d$ define $k_i = |\Gamma_i(x)|$. In particular, Γ is a regular graph with degree $k = b_0, b_d = c_0 = 0, c_1 = 1$ and $c_i + a_i + b_i = k$ for all $0 \leq i \leq d$. The sequence $\{b_0, \dots, b_{d-1}; c_1, \dots, c_d\}$ is called the *intersection array* of Γ . The *distribution diagram* for a distance-regular graph with intersection array $\{b_0, \dots, b_{d-1}; c_1, \dots, c_d\}$ is shown in Figure 1.1.

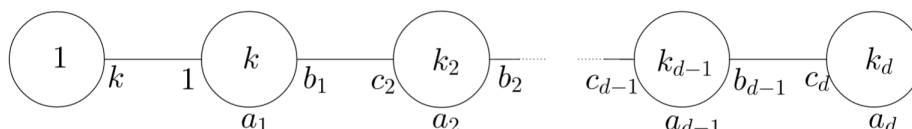


Figure 1.1: Distribution diagram for a distance-regular graph with intersection array $\{b_0, \dots, b_{d-1}; c_1, \dots, c_d\}$.

Example 1.1. The Heawood graph is a distance-regular graph on 14 vertices and diameter 3 with intersection array $\{3, 2, 2; 1, 1, 3\}$. The distribution diagram is shown in Figure 1.3. For a fixed vertex x we display the sets $\Gamma_i(x)$ for $0 \leq i \leq 3$ in Figure 1.4.

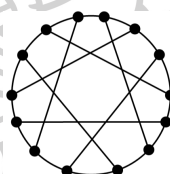


Figure 1.2: The Heawood graph.

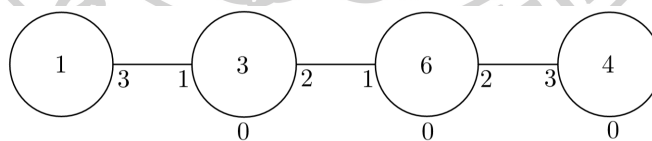


Figure 1.3: Distribution diagram for the Heawood graph.

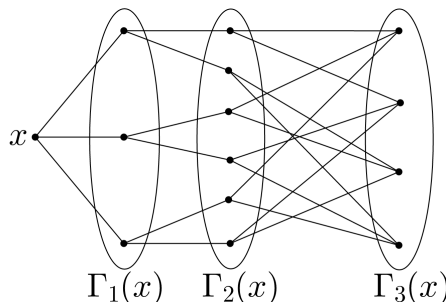


Figure 1.4: Illustration for the sets $\Gamma_i(x)$ of the Heawood graph.

A graph Γ is called *strongly regular* with parameters $(|V(\Gamma)|, k, \lambda, \mu)$ whenever Γ is k -regular, each two adjacent vertices have λ common neighbors, and each two nonadjacent vertices have μ common neighbors. The connected strongly regular graphs are precisely the distance-regular graphs with diameter two and $k = b_0, \lambda = a_1$ and $\mu = c_2$.

For $0 \leq i \leq d$, let A_i denote the $|V(\Gamma)| \times |V(\Gamma)|$ matrix whose rows and columns are indexed by the vertices of Γ and

$$(A_i)_{xy} = \begin{cases} 1 & \text{if } d(x, y) = i, \\ 0 & \text{if } d(x, y) \neq i, \end{cases}$$

where $x, y \in V(\Gamma)$. We call A_i the *i -th distance matrix* of Γ . In particular, we call $A = A_1$ the *adjacency matrix* of Γ . By construction the matrix A_i is real and symmetric for $0 \leq i \leq d$.

The *eigenvalues* of Γ are the eigenvalues of its adjacency matrix. Since an adjacency matrix is real and symmetric, its eigenvalues are real numbers. The *multiplicity* of an eigenvalue θ is the multiplicity of the root θ of the characteristic equation $\det(\alpha I - A) = 0$. The *spectrum* of a graph is the set of numbers which are eigenvalues together with their multiplicities. If the distinct eigenvalues of a graph are $\theta_0 > \theta_1 > \dots > \theta_d$ and their multiplicities are m_0, m_1, \dots, m_d , respectively, then we write the spectrum of the graph as $\theta_0^{m_0} \theta_1^{m_1} \dots \theta_d^{m_d}$.

An *incidence geometry* (P, L) consists of a set P whose elements are called points and a set L whose elements are called lines together with an incidence relation between points and lines, that is, a subset of $P \times L$. A *partial linear space* is an incidence geometry such that every pair of distinct points lie on at most one common line and every line has at least two points.

Example 1.2. The Fano plane is a partial linear space with 7 points and 7 lines and each line has 3 points.

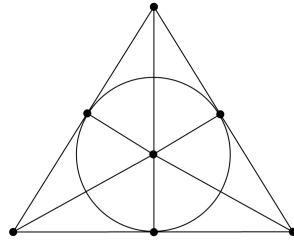


Figure 1.5: The Fano plane.

There are many results concerning existence and nonexistence of distance-regular graphs, as example:

In [9] Coolsaet and Degraer proved that there exists a unique distance-regular graph with intersection array $\{6, 5, 2; 1, 1, 3\}$ on 57 vertices. This graph is known as the Perkel graph.

In [5, Theorem 11.2.1 (13)] a distance-regular graph with intersection array $\{31, 30, 17; 1, 2, 15\}$ on 1024 vertices was constructed from studying the Kasami codes.

Brouwer and Pasechnik [6] proved that there exists a distance-regular graph with intersection array $\{26, 24, 19; 1, 3, 8\}$ on 729 vertices by constructing the subgraph of a dual polar graph.

Coolsaet and Jurišić [10] established the nonexistence of a distance-regular graph with intersection array $\{74, 54, 15; 1, 9, 60\}$ and of distance-regular graphs with intersection arrays $\{4r^3 + 8r^2 + 6r + 1, 2r(r + 1)(2r + 1), 2r^2 + 2r + 1; 1, 2r(r + 1), (2r + 1)(2r^2 + 2r + 1)\}$ whrer r is a positive integer by using equality in the Krein conditions.

There are many results that established the nonexistence of distance-regular graphs by studying the local graphs, as example:

Coolsaet [7] proved that a distance-regular graph with intersection array $\{21, 16, 8; 1, 4, 14\}$ does not exist by partitioning a local graph of a hypothetical distance-regular graph and constructing a partial linear space on the partition.

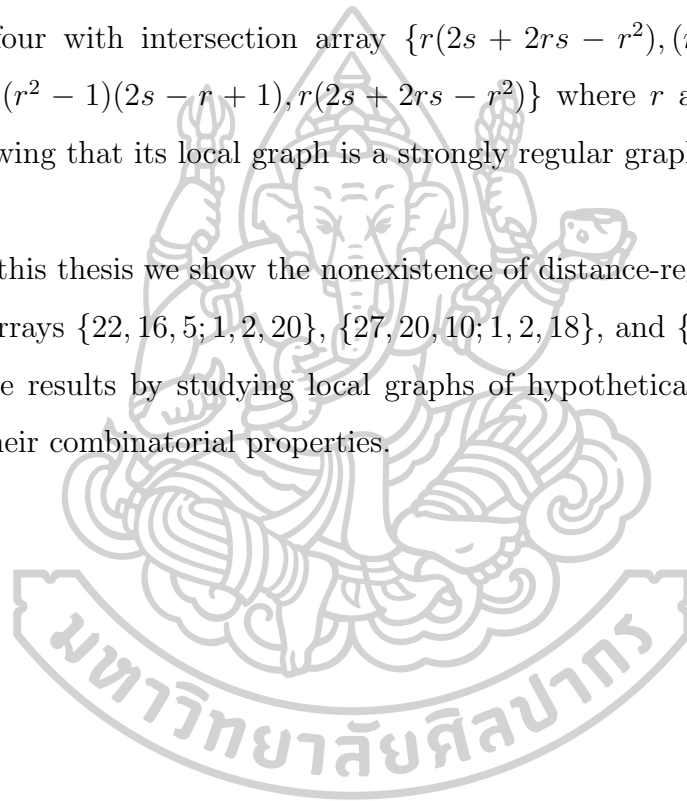
In [8] Coolsaet proved the nonexistence of a distance-regular graph with intersection array $\{13, 10, 7; 1, 2, 7\}$ by showing that its local graph is a disjoint union of triangles, hexagons and/or heptagons.

Coolsaet and Jurišić [10] proved the nonexistence of a distance-regular graph with intersection array $\{19, 12, 5; 1, 4, 15\}$ by showing that its local graph is a strongly regular graph with parameters $(19, 6, 1, 2)$ and it is known that a strongly regular graph with these parameters does not exist.

In [12] Gavriljuk proved that distance-regular graphs with intersection arrays $\{55, 36, 11; 1, 4, 45\}$ and $\{56, 36, 9; 1, 3, 48\}$ do not exist by considering the coclique of local graphs.

Jurišić and Koolen [13] proved that there is no distance-regular graph of diameter four with intersection array $\{r(2s + 2rs - r^2), (r^2 - 1)(2s - r + 1), rs, 1; 1, rs, (r^2 - 1)(2s - r + 1), r(2s + 2rs - r^2)\}$ where r and s are odd integers by showing that its local graph is a strongly regular graph and considering its property.

In this thesis we show the nonexistence of distance-regular graphs with intersection arrays $\{22, 16, 5; 1, 2, 20\}$, $\{27, 20, 10; 1, 2, 18\}$, and $\{36, 28, 4; 1, 2, 24\}$. We obtain the results by studying local graphs of hypothetical distance-regular graphs and their combinatorial properties.



Chapter 2

Distance-Regular Graphs

In this chapter we provide some background and known results about distance-regular graphs. From now on we assume that Γ is a distance-regular graph with degree k and diameter d .

The following results are necessary conditions for the intersection arrays of distance-regular graphs.

Lemma 2.1. (See [5, pp. 127].) *For $0 \leq i \leq d-1$,*

(i) $k_0 = 1$,

(ii) $k_1 = k$,

(iii) $k_{i+1}c_{i+1} = k_i b_i$,

(iv) $|V(\Gamma)| = 1 + k_1 + k_2 + \cdots + k_d$.

Proof. (i), (ii), (iv) follow from the definition of a distance-regular graph.

(iii) holds because each of $k_{i+1}c_{i+1}$ and $k_i b_i$ is equal to the number of edges between $\Gamma_i(x)$ and $\Gamma_{i+1}(x)$. □

Proposition 2.2. (See [5, Proposition 4.1.6].) *The following conditions hold:*

(i) $k = b_0 > b_1 \geq b_2 \geq \cdots \geq b_{d-1} > b_d = 0$,

(ii) $1 = c_1 \leq c_2 \leq \cdots \leq c_d \leq k$,

(iii) if $i + j \leq d$, then $c_i \leq b_j$,

(iv) there exists an i such that $k_0 \leq k_1 \leq \cdots \leq k_i$ and $k_{i+1} \geq k_{i+2} \geq \cdots \geq k_d$,

(v) all multiplicities are integers.

Proof. (i) For $1 \leq i \leq d$, let $x, y, z \in V(\Gamma)$ such that $d(x, y) = i$ and $z \in \Gamma_1(x) \cap \Gamma_{i-1}(y)$. Let $w \in \Gamma_1(y) \cap \Gamma_{i+1}(x)$. Then $d(w, z) = i$ and thus $w \in \Gamma_1(y) \cap \Gamma_i(z)$. Thus $\Gamma_1(y) \cap \Gamma_{i+1}(x) \subseteq \Gamma_1(y) \cap \Gamma_i(z)$. So $b_i = |\Gamma_1(y) \cap \Gamma_{i+1}(x)| \leq |\Gamma_1(y) \cap \Gamma_i(z)| = b_{i-1}$.

(ii) For $1 \leq i \leq d$, let $x, y, z \in V(\Gamma)$ such that $d(x, y) = i$ and $z \in \Gamma_1(x) \cap \Gamma_{i-1}(y)$. Let $w \in \Gamma_1(y) \cap \Gamma_{i-2}(z)$. Then $d(w, x) = i - 1$ and so $w \in \Gamma_1(y) \cap \Gamma_{i-1}(x)$. Thus $\Gamma_1(y) \cap \Gamma_{i-2}(z) \subseteq \Gamma_1(y) \cap \Gamma_{i-1}(x)$. Therefore $c_{i-1} = |\Gamma_1(y) \cap \Gamma_{i-2}(z)| \leq |\Gamma_1(y) \cap \Gamma_{i-1}(x)| = c_i$.

(iii) Suppose that $i + j \leq d$. Let $x, y, z \in V(\Gamma)$ such that $d(x, y) = i + j$ and $z \in \Gamma_i(x) \cap \Gamma_j(y)$. Let $w \in \Gamma_1(z) \cap \Gamma_{i-1}(x)$. Then $d(w, y) = j + 1$ and hence $w \in \Gamma_1(z) \cap \Gamma_{j+1}(y)$. So $\Gamma_1(z) \cap \Gamma_{i-1}(x) \subseteq \Gamma_1(z) \cap \Gamma_{j+1}(y)$. Therefore $c_i = |\Gamma_1(z) \cap \Gamma_{i-1}(x)| \leq |\Gamma_1(z) \cap \Gamma_{j+1}(y)| = b_j$.

(iv) By (i),(ii) and Lemma 2.1 (iii), we have $k_j/k_{j+1} = c_{j+1}/b_j \leq c_{j+2}/b_{j+1} = k_{j+1}/k_{j+2}$. Then there exists a i such that $k_0 \leq k_1 \leq \dots \leq k_i$ and $k_{i+1} \geq k_{i+2} \geq \dots \geq k_d$

(v) It follows from the definition of multiplicity. \square

The following results give formulas of eigenvalues and their multiplicities of a distance-regular graph.

Lemma 2.3. (See [5, pp. 127].) For $0 \leq i \leq d$,

$$AA_i = c_{i+1}A_{i+1} + a_iA_i + b_{i-1}A_{i-1}$$

where A is the adjacency matrix of Γ , $A_{-1} = A_{d+1} = 0$ and b_{-1} and c_{d+1} are unspecified.

Proof. For $x, y \in V(\Gamma)$, we have

$$\begin{aligned} (AA_i)_{xy} &= \sum_{z \in V(\Gamma)} A_{xz}(A_i)_{zy} \\ &= \sum_{z \in \Gamma_1(x) \cap \Gamma_i(y)} 1 \\ &= |\Gamma_1(x) \cap \Gamma_i(y)| \end{aligned}$$

$$\begin{aligned}
&= \begin{cases} b_{i-1} & \text{if } d(x, y) = i - 1, \\ a_i & \text{if } d(x, y) = i, \\ c_{i+1} & \text{if } d(x, y) = i + 1, \\ 0 & \text{otherwise} \end{cases} \\
&= (c_{i+1}A_{i+1} + a_iA_i + b_{i-1}A_{i-1})_{xy}.
\end{aligned}$$

The result follows. \square

Let λ denote an indeterminate. Define polynomials $\{v_i\}_{i=0}^{d+1}$ by $v_0(\lambda) = 1$, $v_1(\lambda) = \lambda$, and for $1 \leq i \leq d$, $\lambda v_i(\lambda) = c_{i+1}v_{i+1}(\lambda) + a_i v_i(\lambda) + b_{i-1}v_{i-1}(\lambda)$ where $v_{-1}(\theta) = v_{d+1}(\theta) = 0$, and b_{-1} and c_{d+1} are unspecified.

Lemma 2.4. (See [5, pp. 127, 128] and [14, Lemma 3.8].) *The following conditions hold:*

- (i) $\deg v_i = i$ ($0 \leq i \leq d+1$),
- (ii) the coefficient of λ^i in v_i is $(c_1 c_2 \cdots c_i)^{-1}$ ($0 \leq i \leq d+1$),
- (iii) $v_i(A) = A_i$ ($0 \leq i \leq d$),
- (iv) $v_{d+1}(A) = 0$,
- (v) the distinct eigenvalues of Γ are precisely the zeros of v_{d+1} .

Define a $(d+1) \times (d+1)$ matrix B as follows:

$$B = \begin{bmatrix} a_0 & b_0 & & & \mathbf{0} \\ c_1 & a_1 & b_1 & & \\ & c_2 & a_2 & \ddots & \\ & & \ddots & \ddots & b_{d-1} \\ \mathbf{0} & & & c_d & a_d \end{bmatrix}.$$

Observe that $v(\lambda)B = \lambda v(\lambda)$ where $v(\lambda) = (v_0(\lambda), v_1(\lambda), \dots, v_d(\lambda))$. So $v(\lambda)$ is an eigenvector of B corresponding to eigenvalue λ . The minimum polynomial of B

has degree $d + 1$ and satisfies $a_d v_d(\lambda) + b_{d-1} v_{d-1}(\lambda) = \lambda v_d(\lambda)$ that is $\lambda v_d(\lambda) - a_d v_d(\lambda) - b_{d-1} v_{d-1}(\lambda) = 0$. By Lemma 2.3 and Lemma 2.4, the adjacency matrix A has the same minimal polynomial as B . Moreover the minimal polynomial of B is the characteristic polynomial of B .

Proposition 2.5. (See [2, Proposition 21.2].) Γ has $d + 1$ distinct eigenvalues $k = \theta_0 > \theta_1 > \dots > \theta_d$ which are the eigenvalues of the matrix B .

Theorem 2.6. (Biggs' formula) (See [2, Theorem 21.4].) Let θ denote an eigenvalue of Γ . Then the multiplicity $m(\theta)$ of θ satisfies

$$m(\theta) = \frac{|V(\Gamma)|}{\sum_{i=0}^d \frac{(v_i(\theta))^2}{k_i}}.$$

The following proposition gives an upper bound of the size of a clique of a distance-regular graph in terms of its smallest and largest eigenvalues.

Proposition 2.7. (See [5, Proposition 4.4.6].) Let Γ denote a distance-regular graph of diameter $d \geq 2$ with eigenvalues $k = \theta_0 > \theta_1 > \dots > \theta_d$. Then the size of a clique K in Γ is bounded by

$$|K| \leq 1 - k/\theta_d.$$

Chapter 3

The nonexistence of a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$

In this chapter we investigate a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$. If a distance-regular graph with such array exists, then by Lemma 2.1, the number of vertices is 448 and the valency is 27. By Proposition 2.5 and Theorem 2.6, the spectrum of the graph is $27^1 9^{96} (-1)^{216} (-5)^{135}$ and the distribution diagram is shown in Figure 3.1.

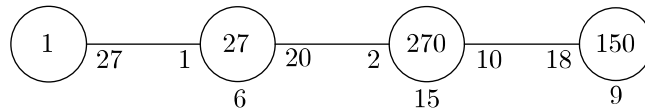


Figure 3.1: Distribution diagram for a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$.

In addition, the distance-three graph is a strongly regular graph with parameters $(243, 150, 50, 50)$ which corresponds to a partial geometry $pg(15, 9, 5)$; according to Brouwer [4], it is unknown whether such a strongly regular graph and a partial geometry exist.

In this chapter we prove the nonexistence of a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$. In particular we assume that such a graph exists and derive some combinatorial properties of its local graph to display the contradiction.

The following results are combinatorial properties of a distance-regular graph.

Lemma 3.1. *Let Γ denote a distance-regular graph and fix a vertex ∞ of Γ . Then each vertex in $\Gamma_1(\infty)$ is on at least $\lceil \frac{1}{2}(a_1^2 + 1 - |\Gamma_1(\infty)|) \rceil$ triangles.*

Proof. Let u denote a vertex of $\Gamma_1(\infty)$. Let u_1, u_2, \dots, u_{a_1} denote the distinct neighbors of u in $\Gamma_1(\infty)$. Let N denote the number of triangles of $\Gamma_1(\infty)$ that contain u . Observe that N is also the number of edges $u_i u_j$ where $1 \leq i < j \leq a_1$. Thus the number of vertices of $\Gamma_1(\infty)$ with distance at most 2 from u is $1 + a_1 + (a_1 - 1)a_1 - 2N$. Therefore a vertex u is on at least $\lceil \frac{1}{2}(a_1^2 + 1 - |\Gamma_1(\infty)|) \rceil$ triangles in $\Gamma_1(\infty)$. \square

Lemma 3.2. *Let Γ denote a distance-regular graph with $c_2 = 2$. Fix a vertex ∞ of Γ . Let $\Delta = \Gamma_1(\infty)$ denote the subgraph of Γ induced by all vertices of Γ adjacent to ∞ . If Δ contains a cycle C of length 4, then the subgraph induced by C is a complete graph K_4 .*

Proof. Suppose that Δ contains a cycle C of length 4. Suppose there exist vertices u and v of C that are not adjacent in Δ . Then the distance between u and v is 2 and there exist two distinct paths from u to v of length 2 in C and a path $u\infty v$ in Γ which contradicts the fact that $c_2 = 2$. Thus any two distinct vertices of C are adjacent. Therefore the subgraph induced by C is a complete graph K_4 . \square

From now on we assume that Γ is a distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$. Then Γ has eigenvalues 27, 9, -1 and -5 . Fix a vertex ∞ of Γ . Let $\Delta = \Gamma_1(\infty)$ denote the subgraph of Γ induced by all vertices of Γ adjacent to ∞ . Then Δ is a 6-regular graph on 27 vertices. The following results give some properties of the local graph Δ . By Lemma 3.2 we have that two nonadjacent vertices in Δ have at most one common neighbor in Δ .

Corollary 3.3. *Δ does not contain a complete subgraph K_i for all $i \geq 6$.*

Proof. By Proposition 2.7, the size of a clique in Γ is at most 6. Thus the size of a clique in Δ is at most 5. \square

Lemma 3.4. *Each vertex in Δ is on at least six subgraphs K_3 's of Δ .*

Proof. Let u denote a vertex of Δ and $u_1, u_2, u_3, u_4, u_5, u_6$ denote the distinct neighbors of u in Δ . From Lemma 3.1 the number of edges $u_i u_j$ for $1 \leq i < j \leq 6$ is at least 5. By the pigeonhole principle, there exists one vertex of $\{u_i | 1 \leq i \leq 6\}$

which is incident with at least 2 edges of the N edges $u_i u_j$ so we may assume that u_1 is adjacent to u_2 and u_3 . By Lemma 3.2 applied to the cycle $u u_2 u_1 u_3$, the vertices u_2 and u_3 are adjacent. Thus u is on at least six subgraphs K_3 's of Δ . \square

By Lemma 3.2, Corollary 3.3 and Lemma 3.4, there are 3 possibilities for the subgraph of Δ induced by a vertex w and its neighbors as shown in Figure 3.2.

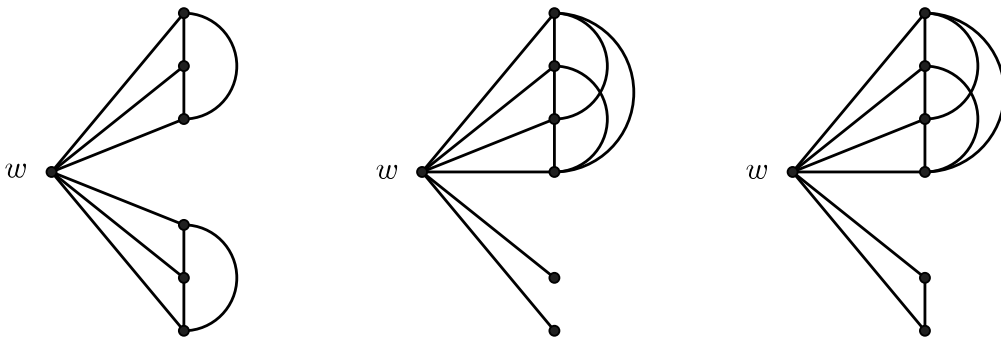


Figure 3.2: The 3 possibilities for the subgraph of Δ induced by a vertex w and its neighbors.

Lemma 3.5. Δ contains a complete subgraph K_5 .

Proof. Suppose that there is no a complete subgraph K_5 in Δ . Then we have the first possibility of Figure 3.2, that is, each vertex is on two subgraphs K_4 's of Δ . Thus the total number of subgraphs K_4 's in Δ is $27 \times 2/4$, a contradiction. \square

Observe that we always have the second or the third possibility of Figure 3.2. The number of subgraphs K_5 's in Δ is $27/5$, but that is not an integer, a contradiction. Therefore such graph Γ does not exist and we have the following theorem.

Theorem 3.6. A distance-regular graph with intersection array $\{27, 20, 10; 1, 2, 18\}$ does not exist.

Chapter 4

The nonexistence of a distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$

In this chapter we consider the intersection array $\{36, 28, 4; 1, 2, 24\}$ [5, pp. 428]. If a distance-regular graph with such array exists, then by Lemma 2.1, the number of vertices is $625 = 5^4$ and the valency is 36. By Proposition 2.5 and Theorem 2.6, the spectrum of the graph is $36^1 11^{84} 6^{120} (-4)^{420}$ and the distribution diagram is shown in Figure 4.1.

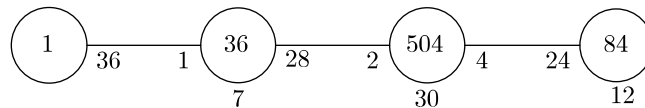


Figure 4.1: Distribution diagram for a distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$.

In addition, the distance-two graph is a strongly regular graph with parameters $(625, 504, 403, 420)$ which corresponds to an orthogonal array $OA(25, 21)$; according to Brouwer [4], such a strongly regular graph exists.

In this chapter we apply the result in Chapter 3 to prove the nonexistence of a distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$. In particular we assume that such a graph exists and show that its local graph is a disjoint union of complete graphs K_8 's to get a contradiction.

From now on we assume that Γ is a distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$. Then Γ has eigenvalues 36, 11, 6 and -4 . Fix a vertex ∞ of Γ . Let $\Delta = \Gamma_1(\infty)$ denote the subgraph of Γ induced by all vertices of Γ adjacent to ∞ . Then Δ is a 7-regular graph on 36 vertices.

Corollary 4.1. *Each vertex in Δ is on at least seven complete subgraphs K_3 's of Δ .*

Proof. The result follows from Lemma 3.1. \square

By Lemma 3.2 and Corollary 4.1, there are 6 possibilities for the subgraph of Δ induced by a vertex u and its neighbors as shown in Figure 4.2.

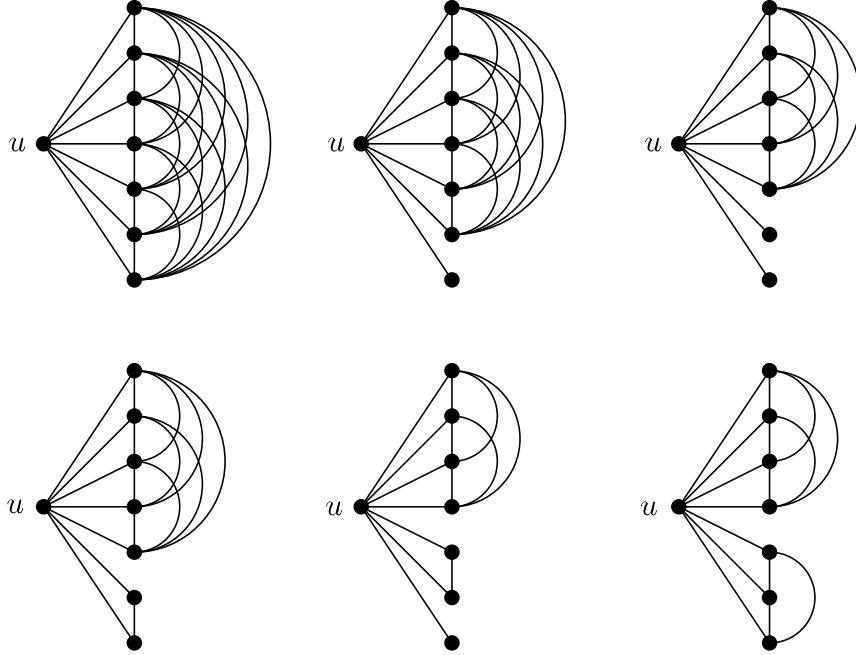


Figure 4.2: The 6 possibilities for the subgraph of Δ induced by a vertex u and its neighbors.

Observe that each vertex of Δ is on a complete subgraph K_5 . The following three lemmas show that a vertex of Δ and its neighbors induce a complete subgraph K_8 .

Lemma 4.2. *Each vertex of Δ is on a complete subgraph K_6 .*

Proof. Let u denote a vertex of Δ . Let K denote a complete subgraph K_5 that contains u . Let $K = \{u, v, w, x, y\}$. For $t \in K$, let $N_{\Delta-K}(t) = \{t_1, t_2, t_3\}$. We first show that there exist two distinct vertices in K which have a common neighbor in $\Delta - K$. Suppose not. Then u_i, v_i, w_i, x_i and y_i are distinct for all $1 \leq i \leq 3$. Let u_{i1}, u_{i2}, u_{i3} and u_{i4} denote neighbors of u_i such that $u_i, u_{i1}, u_{i2}, u_{i3}$ and u_{i4} induce a complete subgraph K_5 for $1 \leq i \leq 3$. Then $u_j \notin \{u_{i1}, u_{i2}, u_{i3}, u_{i4}\}$ for $i \neq j$ by Lemma 3.2. The vertices u_{ij} and u_{lm} are distinct for all $1 \leq i < l \leq 3$

and $1 \leq j, m \leq 4$ by Lemma 3.2. Since Δ has 36 vertices, we let $\Delta - (K \cup \{u_i, v_i, w_i, x_i, y_i, u_{ij} | 1 \leq i \leq 3, 1 \leq j \leq 4\}) = \{s_1, s_2, s_3, s_4\}$. By Lemma 3.2, the vertex v_1 is adjacent to at most one vertex in $\{u_{ij} | 1 \leq j \leq 4\}$ for each $1 \leq i \leq 3$ and v_1 is not adjacent to u_j, w_j, x_j and y_j for all $1 \leq j \leq 3$. Without loss of generality, we may assume that v_1 is adjacent to s_1 . By Lemma 3.2, the vertices v_2 and v_3 are not adjacent to s_1 . By similar arguments, we may assume that v_2 is adjacent to s_2 , and v_3 is adjacent to s_3 . Then v_1 is not adjacent to s_2 or s_3 by Lemma 3.2. By Corollary 4.1 applied to v , we may assume that v_1 and v_2 are adjacent. Since v_1 has degree 7 and v_1 is not adjacent to s_2 or s_3 , we may assume that v_1 is adjacent to u_{11} and u_{21} . By Corollary 4.1 applied to v_1 , the subgraph induced by a vertex v_1 and its neighbors except v and v_2 contains a complete subgraph K_5 and we may assume that u_{11} is on such a subgraph. It follows that u_{11} has degree at least 8, a contradiction. Thus there exist two distinct vertices in K which have a common neighbor in $\Delta - K$. Without loss of generality, we may assume that u and v have a common neighbor in $\Delta - K$, say z . Then z is adjacent to w, x and y by Lemma 3.2. The subgraph induced by u, v, w, x, y and z is a complete graph K_6 . \square

Lemma 4.3. *Each vertex of Δ is on a complete subgraph K_7 .*

Proof. Let u denote a vertex of Δ . Let F denote a complete subgraph K_6 that contains u . Let $F = \{u, v, w, x, y, z\}$. For $t \in F$, let $N_{\Delta-F}(t) = \{t_1, t_2\}$. We first show that there exist two distinct vertices in F which have a common neighbor in $\Delta - F$. Suppose not. Then u_i, v_i, w_i, x_i, y_i and z_i are distinct for all $1 \leq i \leq 2$. By Lemma 3.2, the vertex u_i is not adjacent to v_j, w_j, x_j, y_j and z_j for all $1 \leq i, j \leq 2$. Let $u_{i1}, u_{i2}, u_{i3}, u_{i4}$ and u_{i5} denote neighbors of u_i such that $u_i, u_{i1}, u_{i2}, u_{i3}, u_{i4}$ and u_{i5} induce a complete subgraph K_6 for $1 \leq i \leq 2$. Then $u_j \notin \{u_{i1}, u_{i2}, u_{i3}, u_{i4}, u_{i5}\}$ for $i \neq j$ by Lemma 3.2. The vertices u_{ij} and u_{lm} are distinct for all $1 \leq i < l \leq 2$ and $1 \leq j, m \leq 5$ by Lemma 3.2. Since Δ has 36 vertices, we let $\Delta - (F \cup \{u_i, v_i, w_i, x_i, y_i, z_i, u_{ij} | 1 \leq i \leq 2, 1 \leq j \leq 5\}) = \{s_1, s_2, \dots, s_8\}$. Consider a vertex v_1 . By Lemma 3.2, the vertex v_1 is adjacent to at most one vertex in $\{u_{ij} | 1 \leq j \leq 5\}$ for each $1 \leq i \leq 2$ and the vertex v_1 is not adjacent to u_j, w_j, x_j, y_j and z_j for all

$1 \leq j \leq 2$. Without loss of generality, we may assume that v_1 is adjacent to s_i for all $1 \leq i \leq 3$. By Lemma 3.2, the vertex v_2 is not adjacent to s_i for all $1 \leq i \leq 3$. By similar arguments, we may assume that v_2 is adjacent to s_i for all $4 \leq i \leq 6$. Consider a vertex w_1 . By Lemma 3.2, the vertex w_1 is adjacent to at most one vertex in $\{u_{ij} | 1 \leq j \leq 5\}$ for each $1 \leq i \leq 2$, at most one vertex in $\{s_1, s_2, s_3\}$, at most one vertex in $\{s_4, s_5, s_6\}$ and w_1 is not adjacent to u_j, v_j, x_j, y_j and z_j for all $1 \leq j \leq 2$. We may assume that w_1 is adjacent to s_7 . By Lemma 3.2, the vertex w_2 is not adjacent to s_7 . By similar arguments, we assume that w_2 is adjacent to s_8 . Consider the vertices x_1, x_2, y_1, y_2, z_1 and z_2 . By similar arguments, we may assume that x_1, y_1 and z_1 are adjacent to s_7 and x_2, y_2 and z_2 are adjacent to s_8 . Then s_7 is on at most six complete subgraphs K_3 's of Δ which contradicts Corollary 4.1. Thus there exist two distinct vertices in F which have a common neighbor in $\Delta - F$. Without loss of generality, we may assume that u and v have a common neighbor in $\Delta - F$, say t . Then t is adjacent to w, x, y and z by Lemma 3.2. The subgraph induced by t, u, v, w, x, y and z is a complete graph K_7 . \square

Lemma 4.4. *Each vertex of Δ is on a complete subgraph K_8 .*

Proof. Let u denote a vertex of Δ . Let G denote a complete subgraph K_7 that contains u . Let $G = \{t, u, v, w, x, y, z\}$. For $s \in G$, let $N_{\Delta-G}(s) = \{s_1\}$. We first show that there exist two distinct vertices in G which have a common neighbor in $\Delta - G$. Suppose not. Then $t_1, u_1, v_1, w_1, x_1, y_1$ and z_1 are distinct. By Lemma 3.2, the vertex t_1 is not adjacent to u_1, v_1, w_1, x_1, y_1 and z_1 . Let $N_{\Delta-G}(t_1) = \{t_{1i} | 1 \leq i \leq 6\}$. By Corollary 4.1, Lemma 4.2 and Lemma 4.3 applied to t_1 , the vertices t_{1i} and t_{1j} are adjacent for all $1 \leq i < j \leq 6$. By Lemma 3.2, the vertex u_1 is adjacent to at most one vertex in $\{t_{1i} | 1 \leq i \leq 6\}$. By Corollary 4.1, Lemma 4.2 and Lemma 4.3 applied to u_1 , there exist six vertices $u_{11}, u_{12}, u_{13}, u_{14}, u_{15}$ and u_{16} of $\Delta - (G \cup \{t_1, u_1, v_1, w_1, x_1, y_1, z_1, t_{1i} | 1 \leq i \leq 6\})$ such that u_{1i} is adjacent u_1 and u_{1j} for all $1 \leq i < j \leq 6$. By similar arguments, any pair of vertices among $t_1, u_1, v_1, w_1, x_1, y_1$ and z_1 are not adjacent and do not have common neighbors. Therefore, $|\Delta| \geq 7 + 7 + 7 \times 6 = 56$ vertices, a contradiction. Thus there exist two

distinct vertices in G which have a common neighbor in $\Delta - G$. Without loss of generality, we may assume that u and v have a common neighbor in $\Delta - G$, say s . Then s is adjacent to t, w, x, y and z by Lemma 3.2. Observe that the subgraph induced by s, t, u, v, w, x, y and z is a complete graph K_8 . \square

By Lemma 4.4 and since Δ is 7-regular, each component of Δ is a complete graph K_8 . Since $|\Delta| = 36$ and $8 \nmid 36$, such graph Γ does not exist and we have the following theorem.

Theorem 4.5. *A distance-regular graph with intersection array $\{36, 28, 4; 1, 2, 24\}$ does not exist.*



Chapter 5

The nonexistence of a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$

In this chapter we prove that a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$ does not exist. Our construction is inspired by [7] where the author cleverly partitioned a local graph of a hypothetical distance-regular graph with intersection array $\{21, 16, 8; 1, 4, 14\}$ and constructed a partial linear space on the partition. If a distance-regular graph with such array exists, then by Lemma 2.1, the number of vertices is $243 = 3^5$, which is relatively small, and the valency is 22. By Proposition 2.5 and Theorem 2.6, the spectrum of the graph is $22^{1766}(-2)^{132}(-5)^{44}$ and the distribution diagram is shown in Figure 5.1.

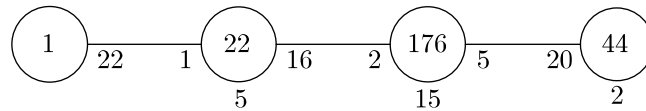


Figure 5.1: Distribution diagram for a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$.

In addition, the distance-two graph is strongly regular with parameters $(243, 176, 130, 120)$; according to Brouwer [4], it is unknown whether such a strongly regular graph exists. Incidentally, there is a very interesting strongly regular graph on 243 vertices, valency 22, and $\mu = 2$: the Berlekamp-Van Lint-Seidel graph that corresponds to the ternary Golay code [1].

We apply the result in Chapter 3 to show that a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$ does not exist. From now on we assume that Γ is a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$. Eigenvalues of Γ are 22, 7, -2 and -5 . Fix a vertex ∞ of Γ . Let $\Delta = \Gamma_1(\infty)$ denote the subgraph of Γ induced by all vertices of Γ adjacent to ∞ . Then Δ is

a 5-regular graph on 22 vertices. The following results give some combinatorial properties of the local graph Δ of Γ .

Corollary 5.1. Δ does not contain a complete subgraph K_i for all $i \geq 5$.

Proof. By Proposition 2.7, the size of a clique in Γ is at most 5. Thus the size of a clique in Δ is at most 4. \square

Lemma 5.2. Each vertex in Δ is on at least two subgraphs K_3 's of Δ .

Proof. Observe that $a_1 = 5$. By Lemma 3.1, the result follows. \square

By Lemma 3.2, Corollary 5.1 and Lemma 5.2, there are 3 possibilities for the subgraph of Δ induced by a vertex u and its neighbors as shown in Figure 5.2.

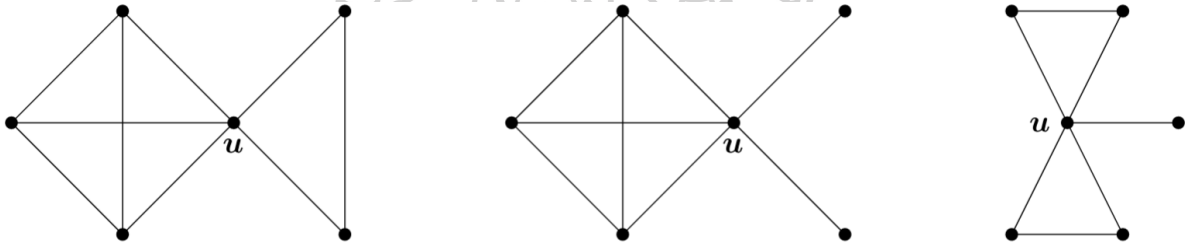


Figure 5.2: The 3 possibilities for the subgraph of Δ induced by a vertex u and its neighbors.

Lemma 5.3. Δ contains a complete subgraph K_4 .

Proof. Suppose not. Then the subgraph of Δ induced by a vertex in Δ and its neighbors must be isomorphic to the graph on the right in Figure 5.2. Thus each vertex in Δ is on exactly two K_3 's so $|\{(u, K_3) | K_3 \subseteq \Delta, u \in K_3\}| = 22 \times 2 = 44$. Since the number of vertices of K_3 is three, $3|44$, a contradiction. Thus Δ contains a complete subgraph K_4 . \square

Now we partition the vertex set of the local graph Δ . For the rest of this chapter, fix a complete subgraph K on four vertices of Δ . Let $S = \Delta_1(K) = \{y \in \Delta - K | y \text{ is adjacent to some vertices in } K\}$ be the neighborhood of K in Δ and define $R = \Delta - K - S$.

Lemma 5.4. *K has size 4, S has size 8, and R has size 10.*

Proof. Clearly, $|K| = 4$. Let u_1, u_2, u_3 and u_4 denote the vertices in K . Since Δ is 5-regular, for each $1 \leq i \leq 4$ there exist two vertices in S which are adjacent to u_i . If u_i and u_j have a common neighbor s in S for some $1 \leq i < j \leq 4$, then by Lemma 3.2, the vertex s is adjacent to u_l for all $1 \leq l \leq 4$ and hence $\{s, u_1, u_2, u_3, u_4\}$ induces a K_5 in Δ which contradicts Corollary 5.1. Thus u_i and u_j have no common neighbors in S for all $1 \leq i < j \leq 4$. Therefore $|S| = 8$, and hence $|R| = |\Delta| - |K| - |S| = 22 - 4 - 8 = 10$. \square

Let u_1, u_2, u_3 and u_4 denote the vertices of K . For $1 \leq i \leq 4$ let s_{2i-1} and s_{2i} denote the vertices of S which are adjacent to u_i .

Lemma 5.5. *The only possible edges in S are $s_{2i-1}s_{2i}$ for $1 \leq i \leq 4$. Moreover, the vertices s_{2i-1} and s_{2i} have no common neighbors in R .*

Proof. The result follows from Lemma 3.2. \square

To further investigate the structure of R we define an incidence geometry $G = (R, S)$ where elements of R are regarded as points and elements of S are regarded as lines, and a point $r \in R$ is on a line $s \in S$ if and only if the vertices r and s are adjacent in Γ .

Lemma 5.6. *G is a partial linear space. Moreover each line in G is incident with at least 3 points.*

Proof. Suppose two distinct points r and r' of R are incident with two distinct lines s and s' . Then the vertices s, r, s' and r' form a cycle in Δ . By Lemma 3.2, the vertices s and s' are adjacent. Thus by Lemma 5.5 the vertices s and s' are adjacent to a common vertex u in K . Now u, s, r and s' form a cycle in Δ . By Lemma 3.2, the vertices u and r are adjacent, a contradiction. Thus every pair of distinct points lie on at most one common line.

By Lemma 5.5 and since Δ is 5-regular, it follows that each vertex of S is adjacent to at least 3 vertices of R , that is, each line in S is incident with at least 3 points in R . Therefore G is a partial linear space. \square

Lemma 5.7. *One of the following two conditions holds:*

- 1). *The number of edges in S is 3. The number of edges in R is 12. The number of edges between S and R is 26.*
- 2). *The number of edges in S is 4. The number of edges in R is 13. The number of edges between S and R is 24.*

Proof. First we will show that the subgraph induced by S contains at least 3 edges.

Without loss of generality, we may assume that s_7 and s_8 are not adjacent. Then s_7 and s_8 are lines of size 4 in G . By Lemma 5.5, the lines s_7 and s_8 have no common points.

Suppose that s_1 is a line of size 4 in G . Then s_1 and s_2 are not adjacent and hence s_2 is also a line of size 4 in G . By Lemma 5.5, the lines s_1 and s_2 have no common points. Since every pair of distinct points lie on at most one common line and $|R| = 10$, the line s_1 is incident with one point of s_7 , one point of s_8 and other two points not on s_7 or s_8 . Similarly, the line s_2 is incident with one point of s_7 , one point of s_8 and two points not on s_1, s_7 or s_8 . Thus G has more than 10 points, a contradiction. Therefore s_1 is a line of size 3 in G . Similarly, s_i is a line of size 3 in G for all $2 \leq i \leq 6$.

Thus s_{2i-1} is adjacent to s_{2i} for all $1 \leq i \leq 3$ and hence the subgraph induced by S contains at least 3 edges.

If S contains exactly 4 edges, then the number of edges between S and R is $3 \times 8 = 24$ and the number of edges in R is $(5 \times 10 - 24)/2 = 13$. If S contains exactly 3 edges, then the number of edges between S and R is $(3 \times 6) + (4 \times 2) = 26$ and the number of edges in R is $(5 \times 10 - 26)/2 = 12$. \square

Lemma 5.8. *Each vertex in R has degree at least 2 in R . Moreover there are at least 4 vertices in R with degree 2 in R .*

Proof. If a vertex r in R is adjacent to 5 vertices in S , then r is adjacent to s_{2i-1} and s_{2i} for some $1 \leq i \leq 4$. The vertices r, s_{2i-1}, u_i and s_{2i} form a cycle in Δ . By Lemma 3.2, the vertices u_i and r are adjacent, a contradiction. Thus each vertex in R is adjacent to at most 4 vertices in S .

Suppose that there exists a vertex r_1 in R such that the number of edges from r_1 to S is 4. By Lemma 3.2, we may assume that r_1 is adjacent to s_1, s_3, s_5 and s_7 . By Lemma 5.2 applied to r_1 , there exist $i, j \in \{1, 3, 5, 7\}$, $i \neq j$, such that s_i and s_j are adjacent which contradicts Lemma 5.5. Thus there are no vertices in R which are adjacent to 4 vertices in S . That is each vertex in R has degree at least 2 in R .

If there are at most 3 vertices in R with degree 2 in R , then the number of edges between R and S is less than or equal to $(3 \times 3) + (7 \times 2) = 23$ which contradicts Lemma 5.7. Thus there are at least 4 vertices in R with degree 2 in R . \square

By Lemma 5.7 and Lemma 5.8, there are 8 possibilities for the degree sequence of R as shown in Table 5.3.

The number of vertices in the induced subgraph R with degree i				$ E(R) $
$i = 2$	$i = 3$	$i = 4$	$i = 5$	
4	6	0	0	13
5	4	1	0	13
6	3	0	1	13
6	2	2	0	13
6	4	0	0	12
7	2	1	0	12
8	0	2	0	12
8	1	0	1	12

Figure 5.3: The 8 possibilities for the degree sequence of R .

By Lemma 5.7, either $|E(R)| = 12$ or $|E(R)| = 13$. We now rule out both possibilities. We start with the latter.

Lemma 5.9. $|E(R)| \neq 13$.

Proof. Suppose that $|E(R)| = 13$. By Lemma 5.7, the subgraph induced by S contains 4 edges and the number of edges between S and R is 24. Thus each vertex in S is adjacent to 3 vertices in R . By Lemma 3.2 and Lemma 5.2, there are 8 distinct edges e_1, e_2, \dots, e_8 in R such that s_i is adjacent to both ends of e_i for $1 \leq i \leq 8$. Let $T = \{e_1, e_2, \dots, e_8\}$.

Suppose that there exists a vertex $r \in R$ which has degree 5 in R . Let r_1, r_2, r_3, r_4 and r_5 denote the distinct neighbors of r in R . Then for each $i \in \{1, 2, 3, 4, 5\}$, $rr_i \notin T$. Since R has 13 edges, $E(R) - \{rr_1, rr_2, rr_3, rr_4, rr_5\} = T$. By Lemma 5.2 applied to r , we may assume that r_1 and r_2 are adjacent. Thus $e_i = r_1r_2$ for some $1 \leq i \leq 8$. So the vertices s_i, r_1, r and r_2 form a cycle in Δ and hence r is adjacent to s_i , a contradiction. Therefore each vertex in R has degree at most 4 in R . By Lemma 5.8, each vertex in R is adjacent to 1, 2 or 3 vertices in S .

Now suppose that r is a vertex in R with degree 3 in R . Let $N_R(r) = \{r_1, r_2, r_3\}$. Without loss of generality, we may assume that $N_S(r) = \{s_1, s_3\}$.

Case 1 : s_i and r_j are not adjacent for all $i \in \{1, 3\}$ and $j \in \{1, 2, 3\}$.

Then r_j and r_k are adjacent for all $1 \leq j < k \leq 3$ by Lemma 5.2 applied to r . By Lemma 3.2, the edges $rr_1, rr_2, rr_3, r_1r_2, r_1r_3, r_2r_3 \notin T$. Since R contains 13 edges, $8 = |T| \leq |E(R) - \{rr_1, rr_2, rr_3, r_1r_2, r_1r_3, r_2r_3\}| = 7$, a contradiction. Thus Case 1 cannot occur.

Case 2 : s_1 is adjacent to exactly one vertex in $\{r_1, r_2, r_3\}$.

Without loss of generality, we may assume that s_1 is adjacent to r_3 . Then s_1 is not adjacent to r_1 and r_2 . Since s_1 is adjacent to 3 vertices in R , there exists a vertex $r_4 \in R - \{r, r_1, r_2, r_3\}$ such that r_4 is adjacent to s_1 . By Lemma 3.2, the vertex s_2 is not adjacent to r_i for $1 \leq i \leq 4$. Since s_2 is adjacent to 3 vertices in R , there exist $r_5, r_6, r_7 \in R - \{r, r_1, r_2, r_3, r_4\}$ such that r_5, r_6, r_7 are adjacent to s_2 . Since R has 10 vertices, there exist $r_8, r_9 \in R - \{r, r_i | 1 \leq i \leq 7\}$. By Lemma 3.2, the vertex r_4 is not adjacent to r_i for $1 \leq i \leq 7$. By Lemma 5.8, the vertex r_4 is adjacent to r_8 and r_9 . By Lemma 3.2, the vertex r_3 is not adjacent to r_i for $1 \leq i \leq 9$. Thus r_3 has degree 1 in R , a contradiction to Lemma 5.8. Hence Case

2 cannot occur.

Case 3 : s_1 is adjacent to exactly two vertices in $\{r_1, r_2, r_3\}$.

Without loss of generality, we may assume that s_1 is adjacent to r_2 and r_3 . Then s_1 is not adjacent to r_1 . By Lemma 3.2, r_2 is adjacent to r_3 , and s_3 is not adjacent to r_2 and r_3 . By Case 2 applied to r and s_3 , the vertex s_3 is not adjacent to r_1 . By Lemma 3.2, the vertex r_1 is not adjacent to s_2 and s_4 . So r_1 has at most two neighbors in S by Lemma 5.5 that is r_1 has degree at least 3 in R . By Lemma 3.2, the vertex r_1 is not adjacent to r_2 and r_3 . Then there exist $r_4, r_5 \in R - \{r, r_1, r_2, r_3\}$ such that r_4, r_5 are adjacent to r_1 . Since each vertex in R is adjacent to at least one vertex in S , we may assume that r_1 is adjacent to s_5 . By Lemma 3.2, the vertex s_3 is not adjacent to r_4 and r_5 . Since s_3 is adjacent to 3 vertices in R , there exist $r_6, r_7 \in R - \{r, r_1, r_2, r_3, r_4, r_5\}$ such that r_6, r_7 is adjacent to s_3 . By Lemma 5.2 applied to s_3 , the vertex r_6 is adjacent to r_7 . By Lemma 3.2, s_4 is not adjacent to $r, r_1, r_2, r_3, r_6, r_7$, and s_4 is adjacent to at most one vertex in $\{r_4, r_5\}$. Since s_4 is adjacent to 3 vertices in R and $|R| = 10$, we may assume that s_4 is adjacent to r_4, r_8 and r_9 where $\{r_8, r_9\} = R - \{r, r_1, r_2, \dots, r_7\}$. Then r_1 and r_8 are not adjacent; otherwise r_1, r_8, s_4 and r_4 form a cycle in Δ and hence r_1 is adjacent to s_4 , a contradiction. Similarly, the vertices r_1 and r_9 are not adjacent. By Lemma 3.2, the vertex r_1 is not adjacent to r_6 and r_7 . Thus r_1 has degree 3 in R . By Lemma 3.2, we may assume that r_1 is adjacent to s_7 . By Case 1 and Case 2 applied to r_1 and s_5 , we may assume that s_5 is adjacent to r_4 and r_5 . Then r_4 and r_5 are adjacent by Lemma 3.2. Since s_2 is adjacent to 3 vertices in R and by Lemma 3.2, the vertex s_2 is adjacent to one vertex in $\{r_4, r_5\}$, one vertex in $\{r_6, r_7\}$ and one vertex in $\{r_8, r_9\}$. Without loss of generality, we may assume that s_2 is adjacent to r_6 and r_8 . Then s_2 and r_4 are not adjacent; otherwise s_2, r_4, s_4 and r_8 form a cycle in Δ and hence s_2 is adjacent to s_4 , a contradiction. Thus s_2 is adjacent to r_5 . The vertices s_7 and r_4 are not adjacent; otherwise the vertices s_7, r_4, s_5 and r_1 form a cycle in Δ and hence s_5 is adjacent to s_7 , a contradiction. By Lemma 3.2, the vertex r_4 is not adjacent to s_6 and s_8 . Thus r_4 has degree 3 in R . The vertex r_4 is not adjacent to r_2 and r_3 ; otherwise the vertices r_4, r_i, r and

r_1 form a cycle in Δ where $i \in \{2, 3\}$ and hence r_4 is adjacent to r , a contradiction. The vertices r_4 and r_6 are not adjacent; otherwise the vertices r_4, r_6, s_3 and s_4 form a cycle in Δ and hence r_4 is adjacent to s_3 , a contradiction. Similarly, the vertex r_4 is not adjacent to r_7 . Hence r_4 is adjacent to either r_8 or r_9 . The vertices r_4 and r_8 are not adjacent; otherwise r_4, r_8, s_2 and r_5 form a cycle in Δ and hence r_4 is adjacent to s_2 , a contradiction. It follows that r_4 is adjacent to r_9 . By Case 2 applied to r_4 and s_4 , the vertex s_4 is adjacent to r_5 . Hence s_4 has degree more than 5 in Δ , a contradiction. Therefore Case 3 cannot occur.

By Case 1, Case 2 and Case 3, $|E(R)| \neq 13$. □

Lemma 5.10. $|E(R)| \neq 12$.

Proof. Suppose that $|E(R)| = 12$. Then the subgraph induced by S contains 3 edges. Without loss of generality, we may assume that s_{2i-1} and s_{2i} are adjacent for $i \in \{1, 2, 3\}$ but s_7 and s_8 are not adjacent. By Lemma 5.7, the number of edges between S and R is 26. By Lemma 3.2 and Lemma 5.2, there are 10 distinct edges e_1, e_2, \dots, e_{10} in R such that s_i is adjacent to both ends of e_i for $1 \leq i \leq 6$, s_7 is adjacent to both ends of e_7 and e_8 and s_8 is adjacent to both ends of e_9 and e_{10} . Let $T = \{e_1, e_2, \dots, e_{10}\}$. By similar arguments as in Lemma 5.9, each vertex in R has degree at most 4 in R .

Suppose that there exists a vertex r in R which has degree 4 in R . Let r_1, r_2, r_3 and r_4 denote distinct neighbors of r in R . Since $|E(R) - T| = 2$, we may assume that $rr_1, rr_2 \in T$ and r is adjacent to s_7 . By Lemma 3.2, the vertex r_1 is adjacent to r_2 . By construction, $r_1r_2 \notin T$. Since rr_1 and rr_2 are two edges with both ends adjacent to s_7 , it follows that $rr_3, rr_4 \notin T$. Hence $13 = |T \cup \{r_1r_2, rr_3, rr_4\}| \leq |E(R)| = 12$, a contradiction. Thus there are no vertices in R which has degree 4 in R .

By Table 5.3, there exist 6 vertices in R with degree 2 in R , and 4 vertices in R with degree 3 in R . By Lemma 5.6, each line in G is incident with at least 3 points. Since s_7 and s_8 are not adjacent, s_7 and s_8 are lines of size 4 in G . By Lemma 5.5, the lines s_7 and s_8 have no common points. Let the point set of G

be $\{r_i | 1 \leq i \leq 10\}$ such that r_3, r_4, r_5, r_6 lie on s_7 and r_7, r_8, r_9, r_{10} lie on s_8 . Note that any line other than s_7 and s_8 must be incidence with either r_1 or r_2 . If r_1 lies on exactly 2 lines, then G has at most 7 lines, a contradiction. Since every vertex in R is adjacent to 2 or 3 vertices in S , r_1 lies on 3 lines in G . Similarly, r_2 lies on 3 lines in G . The points r_1 and r_2 are not on the same line; otherwise G has at most 7 lines, a contradiction. If there exist at least 3 points in s_7 each of which lies on exactly two lines, then G has at most 7 lines, a contradiction. So there are 2 points on the line s_7 which lie on exactly two lines. Similarly, there are 2 points on the line s_8 which lie on exactly two lines. Without loss of generality, we may assume that each of r_5, r_6, r_9 and r_{10} lies on exactly 2 lines and each of r_3, r_4, r_7 and r_8 lies on exactly 3 lines. Then there are 3 possibilities for the incidence geometry G on 10 points and 8 lines satisfying these properties as shown in Figure 5.4.

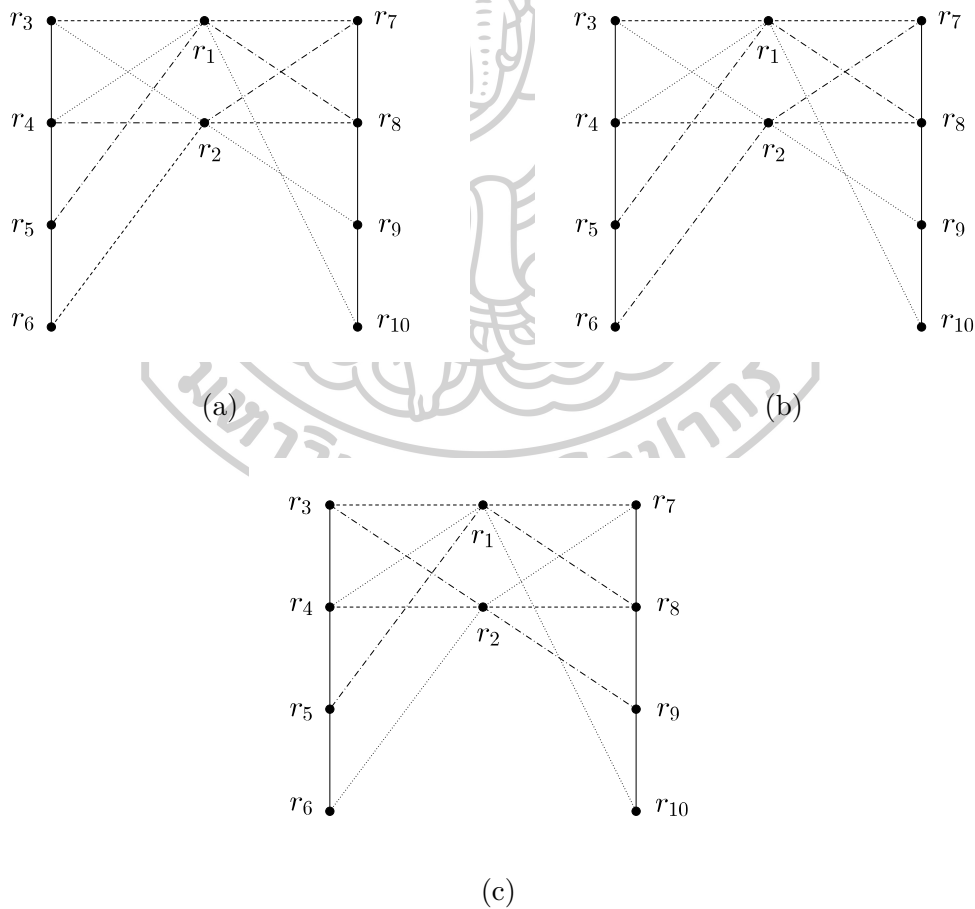


Figure 5.4: The 3 possibilities for the incidence geometry G .

In each figure a pair of solid lines represents s_7 and s_8 , and each pair of nonsolid lines of same style represents s_{2i-1} and s_{2i} for $1 \leq i \leq 3$. If a point r is on a line s_{2i-1} and a point r' is on a line s_{2i} , then the vertex r is not adjacent to r' ; otherwise r, r', s_{2i} and s_{2i-1} form a cycle in Δ , and by Lemma 3.2, the point r is on both s_{2i-1} and s_{2i} , a contradiction. For convenience we call this the parallelity of lines.

In Figure 5.4a, by the parallelity of lines, the vertex r_3 is not adjacent to r_4, r_6 , and the vertex r_5 is not adjacent to r_4 . Suppose that the vertices r_5 and r_6 are adjacent. The vertices r_3 and r_5 are not adjacent; otherwise the vertices r_3, r_5, r_6 and s_7 form a cycle in Δ , and by Lemma 3.2, the vertices r_3 and r_6 are adjacent, a contradiction. The vertices r_4 and r_6 are not adjacent; otherwise the vertices r_4, r_6, r_5 and s_7 form a cycle in Δ , and by Lemma 3.2, the vertices r_4 and r_5 are adjacent, a contradiction. Thus the vertex s_7 is on exactly one subgraph K_3 of Δ which contradicts Lemma 5.2. Hence the vertices r_5 and r_6 are not adjacent. The vertex r_6 is not adjacent to r_i for $i \in \{1, 2\}$; otherwise the vertices r_6, r_i, s_j and r_4 form a cycle in Δ where s_j is the line containing both r_i and r_4 , and by Lemma 3.2, the point r_6 is on s_j , a contradiction. Since r_6 has degree 3 in R , the vertex r_6 is adjacent to 2 vertices u, v in $\{r_7, r_8, r_9, r_{10}\}$. Thus the vertices r_6, u, s_8 and v form a cycle in Δ , and by Lemma 3.2, the point r_6 is on s_8 , a contradiction.

In Figure 5.4b, by the parallelity of lines, the vertex r_3 is not adjacent to r_4 , and the vertex r_5 is not adjacent to r_6 . Since r_2 has degree 2 in R , the vertex r_2 is adjacent to r_6 and r_9 by the parallelity of lines. The vertices r_4 and r_6 are not adjacent; otherwise the vertices r_4, r_6, r_2 and s_j forms a cycle in Δ where s_j is the line containing both r_2 and r_4 , and by Lemma 3.2, the point r_6 is on s_j , a contradiction. Suppose that the vertices r_3 and r_5 are adjacent. The vertices r_3 and r_6 are not adjacent; otherwise the vertices r_3, r_6, s_7 and r_5 form a cycle in Δ , and by Lemma 3.2, the vertices r_5 and r_6 are adjacent, a contradiction. The vertices r_4 and r_5 are not adjacent; otherwise the vertices r_4, r_5, r_3 and s_7 form a cycle in Δ , and by Lemma 3.2, the vertices r_3 and r_4 are adjacent, a contradiction. Hence the vertex s_7 is on exactly one subgraph K_3 of Δ which contradicts Lemma

5.2. Thus the vertices r_3 and r_5 are not adjacent. The vertex r_5 is not adjacent to r_i for $i \in \{1, 2\}$; otherwise the vertices r_5, r_i, s_j and r_4 form a cycle in Δ where s_j is the line containing both r_i and r_4 , and by Lemma 3.2, the point r_5 is on s_j , a contradiction. Since r_5 has degree 3 in R , the vertex r_5 is adjacent to 2 vertices u, v in $\{r_7, r_8, r_9, r_{10}\}$. Thus the vertices r_5, u, s_8 and v form a cycle in Δ , and by Lemma 3.2, the point r_5 is on s_8 , a contradiction.

In Figure 5.4c, by the parallelity of lines, the vertex r_7 is not adjacent to r_8, r_{10} , and the vertex r_9 is not adjacent to r_8 . Suppose that the vertices r_9 and r_{10} are adjacent. The vertices r_7 and r_9 are not adjacent; otherwise the vertices r_7, r_9, r_{10} and s_8 form a cycle in Δ , and by Lemma 3.2, the vertices r_7 and r_{10} are adjacent, a contradiction. The vertices r_8 and r_{10} are not adjacent; otherwise the vertices r_8, r_{10}, r_9 and s_8 form a cycle in Δ , and by Lemma 3.2, the vertices r_8 and r_9 are adjacent, a contradiction. Thus the vertex s_8 is on exactly one subgraph K_3 of Δ which contradicts Lemma 5.2. Hence the vertices r_9 and r_{10} are not adjacent. The vertex r_{10} is not adjacent to r_i for $i \in \{1, 2\}$; otherwise the vertices r_{10}, r_i, s_j and r_8 form a cycle in Δ where s_j is the line containing both r_i and r_8 , and by Lemma 3.2, the point r_{10} is on s_j , a contradiction. Since r_{10} has degree 3 in R , the vertex r_6 is adjacent to 2 vertices u, v in $\{r_3, r_4, r_5, r_6\}$. Thus the vertices r_{10}, u, s_7 and v form a cycle in Δ , and by Lemma 3.2, the point r_{10} is on s_7 , a contradiction. Hence $|E(R)| \neq 12$. \square

By Lemma 5.7, Lemma 5.9 and Lemma 5.10, we have our main result.

Theorem 5.11. *A distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$ does not exist.*

Chapter 6

Conclusions

In this thesis, we study three intersection arrays from the list, $\{22, 16, 5; 1, 2, 20\}$, $\{27, 20, 10; 1, 2, 18\}$, and $\{36, 28, 4; 1, 2, 24\}$. These intersection arrays have $c_2 = 2$, which means that every two nonadjacent vertices have either 0 or 2 common neighbors. We give some combinatorial properties of the local graphs of distance-regular graphs. For a fixed vertex x in a distance-regular graph, we give an upper bound of the number of triangles corresponding to x in term of the intersection numbers a_1 and $b_0 = k$. We show that any two nonadjacent vertices in a local graph have at most one common neighbors. We prove that distance-regular graphs with given intersection arrays from the list do not exist by assuming such graphs exist. For the intersection array $\{27, 20, 10; 1, 2, 18\}$ we derive some combinatorial properties of its local graph to display a contradiction. For the intersection array $\{36, 28, 4; 1, 2, 24\}$ we show that its local graph is a disjoint union of completes K_3 's to get a contradiction. For the intersection array $\{22, 16, 5; 1, 2, 20\}$ we construct a partial linear space from its local graph to display the contradiction.

Potentially it might be possible to adapt our results to check feasibility of some other intersection arrays with $c_2 = 2$. However, more combinatorial properties of individual array need to be investigated.

References

- [1] Berlekamp, E. R., van Lint, J. H., and Seidel J. J. (1973). “A Strongly Regular Graph Derived from the Perfect Ternary Golay Code.” In **A Survey of Combinatorial Theory, Symp. Colorado State Univ., 1971**, 25–30. Edited by Srivastava, Jagdish N., and others. Amsterdam: North Holland.
- [2] Biggs, Norman L. (1974). **Algebraic Graph Theory**. Cambridge: Cambridge University Press.
- [3] Bondy, John A., and Murty, Uppaluri S. R. (1982). **Graph Theory with Applications**. 5th ed. New York: Elsevier Science Publishing.
- [4] Brouwer, Andries E. (2016). **Parameters of strongly regular graphs**. Accessed February 5. Available from <https://www.win.tue.nl/~aeb/graphs/srg/srgtab.html>.
- [5] Brouwer, Andries E., Cohen, Arjeh M., and Neumaier Arnold. (1989). **Distance-regular graphs**, Berlin Heidelberg: Springer-Verlag.
- [6] Brouwer, Andries E., and Pasechnik, Dmitrii V. (2012). “Two distance-regular graphs.” **Journal of Algebraic Combinatorics** 36, 3 (November): 403–407.
- [7] Coolsaet, Kris. (2005). “A distance-regular graph with intersection array $(21,16,8;1,4,14)$ does not exist.” **European Journal of Combinatorics** 26, 5 (July): 709–716.
- [8] Coolsaet, Kris. (1995). “Local structure of graphs with $\lambda = \mu = 2, a_2 = 4$.” **Combinatorica** 15, 4 (December): 481–487.
- [9] Coolsaet, Kris, and Degraer, Jan. (2005). “A computer-assisted proof of the uniqueness of the Perkel graph.” **Designs, Codes and Cryptography** 34, 2–3 (February): 155–171.
- [10] Coolsaet, Kris, and Jurišić, Aleksandar. (2008). “Using equality in the Krein conditions to prove the nonexistence of certain distance-regular graphs.” **Journal of Combinatorial Theory, Series A** 115, 6 (August): 1086–1095.
- [11] van Dam, Edwin R., Koolen, Jack H., and Tanaka Hajime. (2016). “Distance-regular graphs.” **The Electronic Journal of Combinatorics**, dynamic surveys 22 (April): 1–156.
- [12] Gavriluyk, Aleksandr L’vovich. (2011). “Distance-regular graphs with intersection arrays $\{55, 36, 11; 1, , 4, 45\}$ and $\{56, 36, 9; 1, , 3, 48\}$ do not exist.” **Doklady Mathematics** 84, 18 (March): 444–446.

- [13] Jurišić, Aleksandar, and Koolen, Jack H. (2000). “Nonexistence of some antipodal distance-regular graphs of diameter four.” **European Journal of Combinatorics** 21, 1039–1046.
- [14] Terwilliger, Paul. (1992). “The subconstituent algebra of an association scheme I.” **Journal of Algebraic Combinatorics** 1, 20 (June): 363–388.



Publications

- [1] Brouwer, Andries E., Sumalroj, Supalak, and Worawannotai, Chalermpong. (2016). “The nonexistence of distance-regular graphs with intersection arrays $\{27, 20, 10; 1, 2, 18\}$ and $\{36, 28, 4; 1, 2, 24\}$.” **Australasian Journal of Combinatorics** 66(2) (July): 330–332.
- [2] Sumalroj, Supalak, and Worawannotai, Chalermpong. (2016). “The nonexistence of a distance-regular graph with intersection array $\{22, 16, 5; 1, 2, 20\}$.” **The Electronic Journal of Combinatorics**, 23 (1) (February): #P1.32.



Biography

Name	Miss Supalak Sumalroj
Date of Birth	May 6, 1988
Address	26/3 Moo 5 Yaicha, Samphran, Nakhon Pathom, Thailand
Institution Attended	
2009	Bachelor of Science in Mathematics, Silpakorn University
2012	Master of Science in Mathematics, Silpakorn University
2017	Doctor of Philosophy in Mathematics, Silpakorn University

